



NenuFAR and the calibration, imaging, confusion, and decorrelation issues

Cyril Tasse

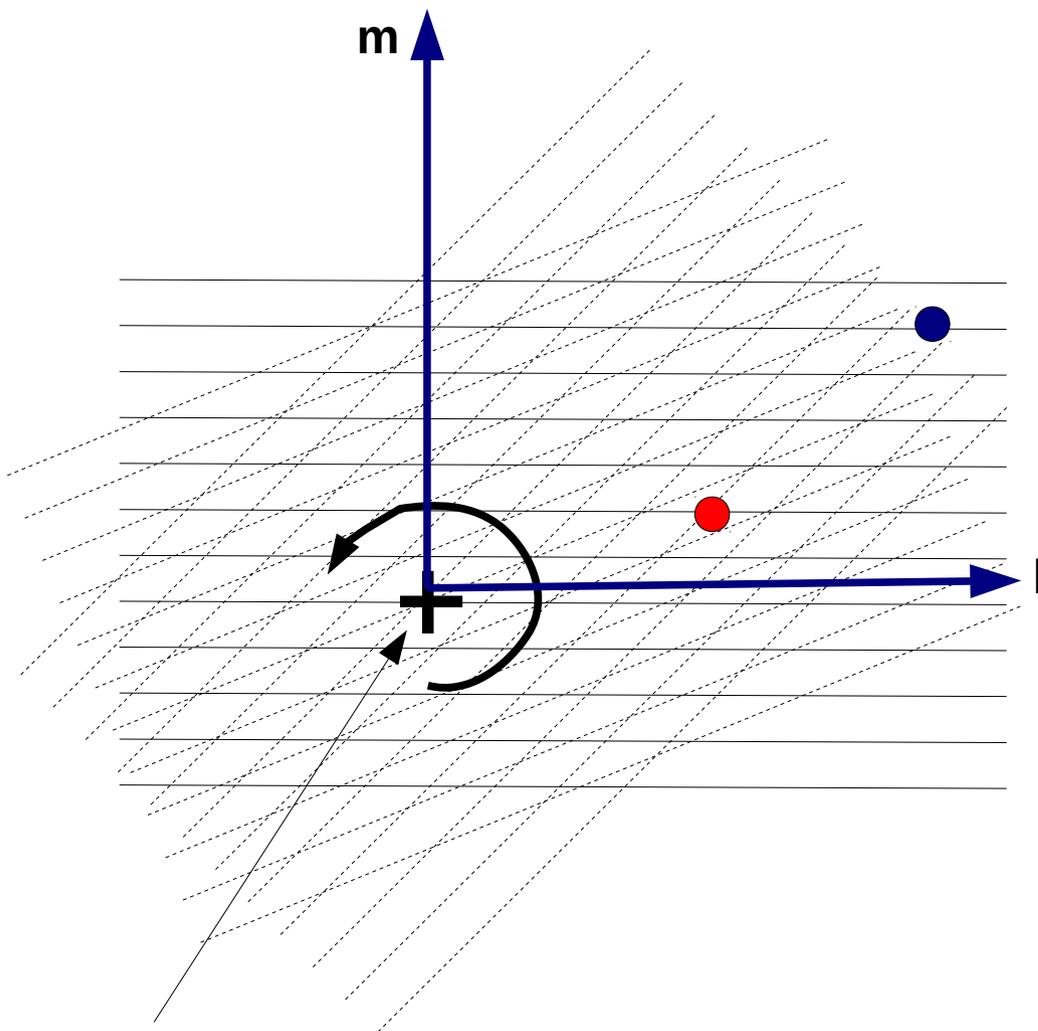
SKA - South Africa (Oleg Smirnov group)
GEPI - Observatoire de Paris

Summary

I am not going to talk about the long-baseline!

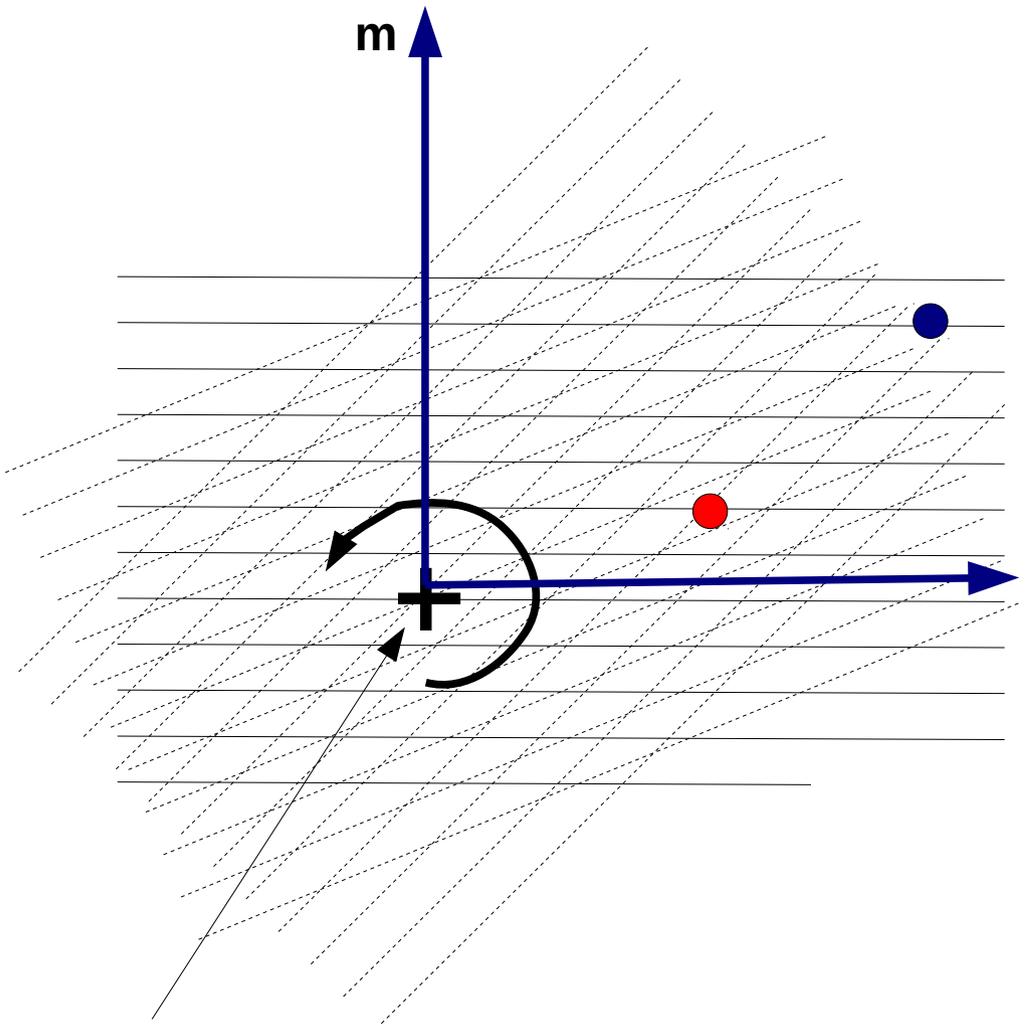
- Decorrelation
- Confusion limit
- Calibration and imaging

Time/Frequency Smearing (“decorrelation”): For one baseline



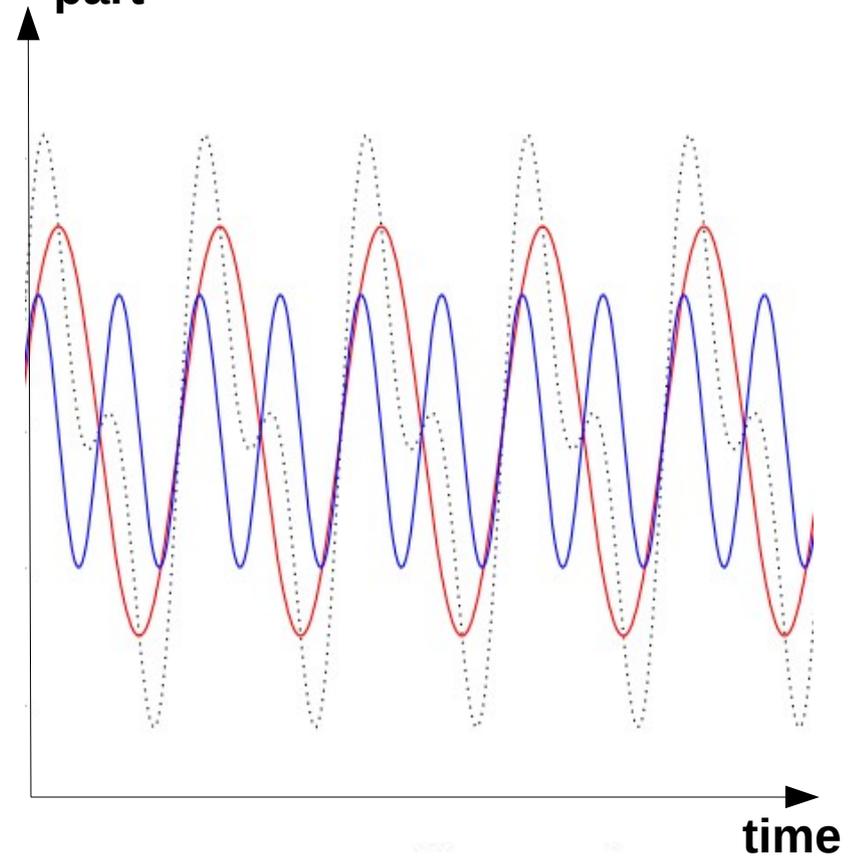
Phase center
("rotation center")

Time/Frequency Smearing (“decorrelation”): For one baseline



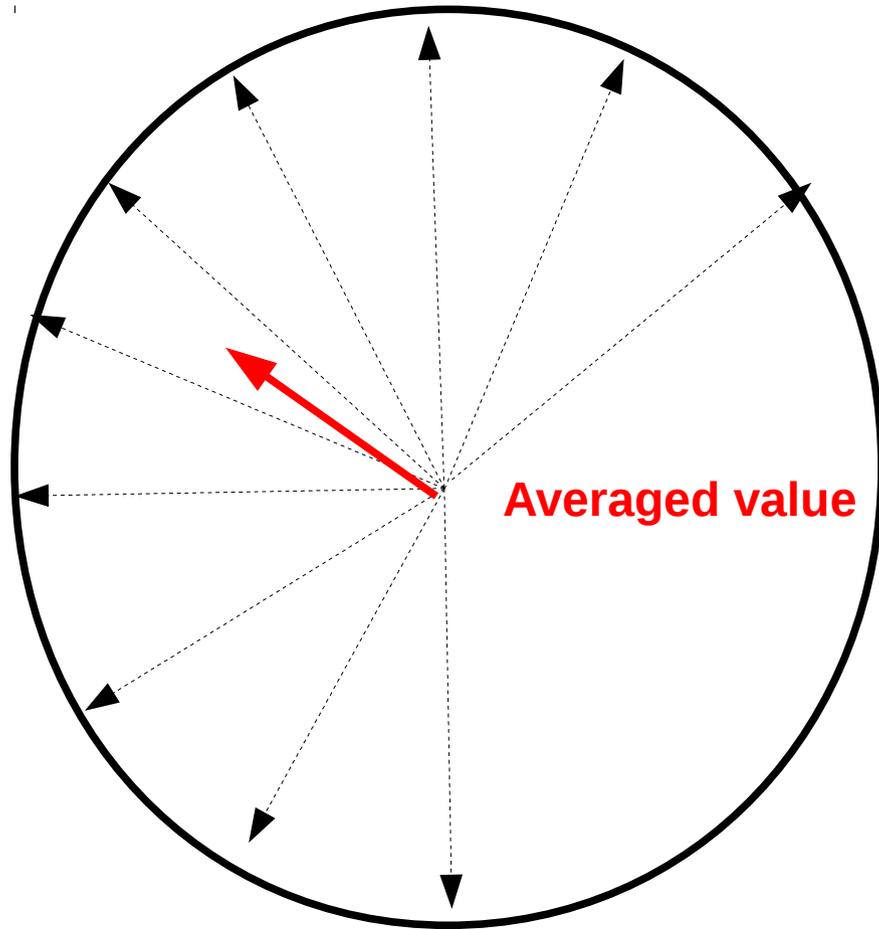
Phase center
("rotation center")

Real/Imaginary
part



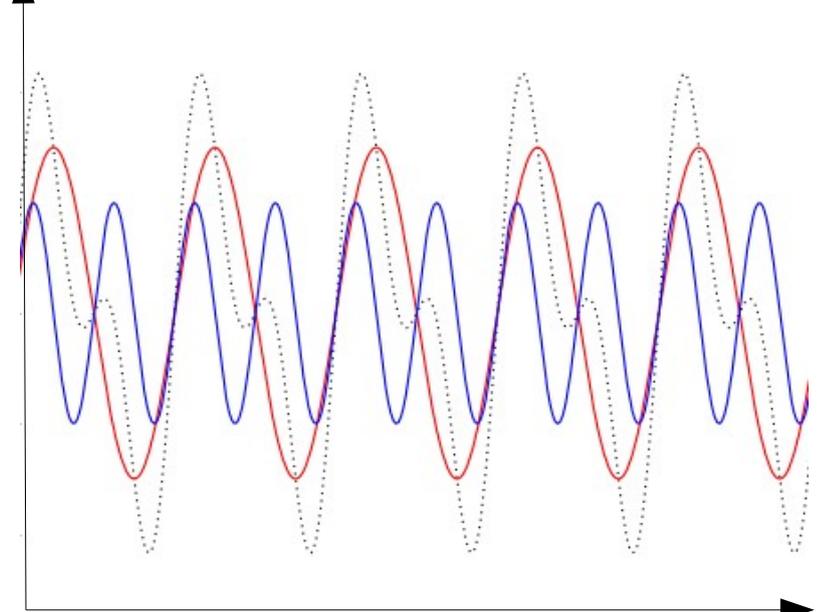
$$\phi_{pq} = u_{pq}l + v_{pq}m + w_{pq}(\sqrt{1 - l^2 - m^2} - 1)$$

Time/Frequency Smearing (“decorrelation”): For one baseline



Real/Imaginary

part



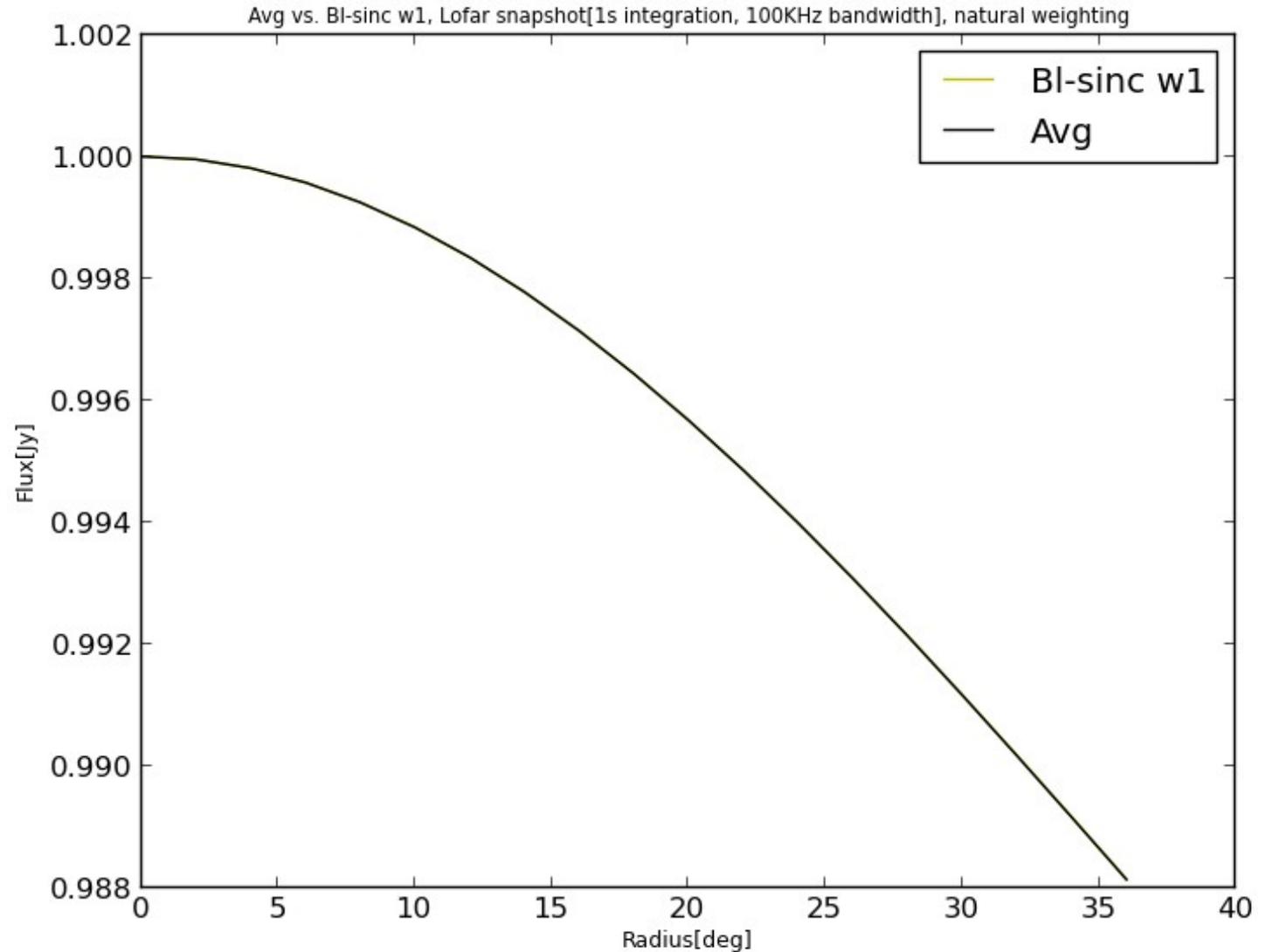
$$K_p K_q^+ = \exp(-2i\pi\phi_{pq}) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\phi_{pq} = u_{pq}l + v_{pq}m + w_{pq}(\sqrt{1 - l^2 - m^2} - 1)$$

Time/Frequency Smearing (“decorrelation”): For one baseline

Simulation for NenuFAR
Courtesy: Oleg Smirnov
And Marcellin Atemkeng

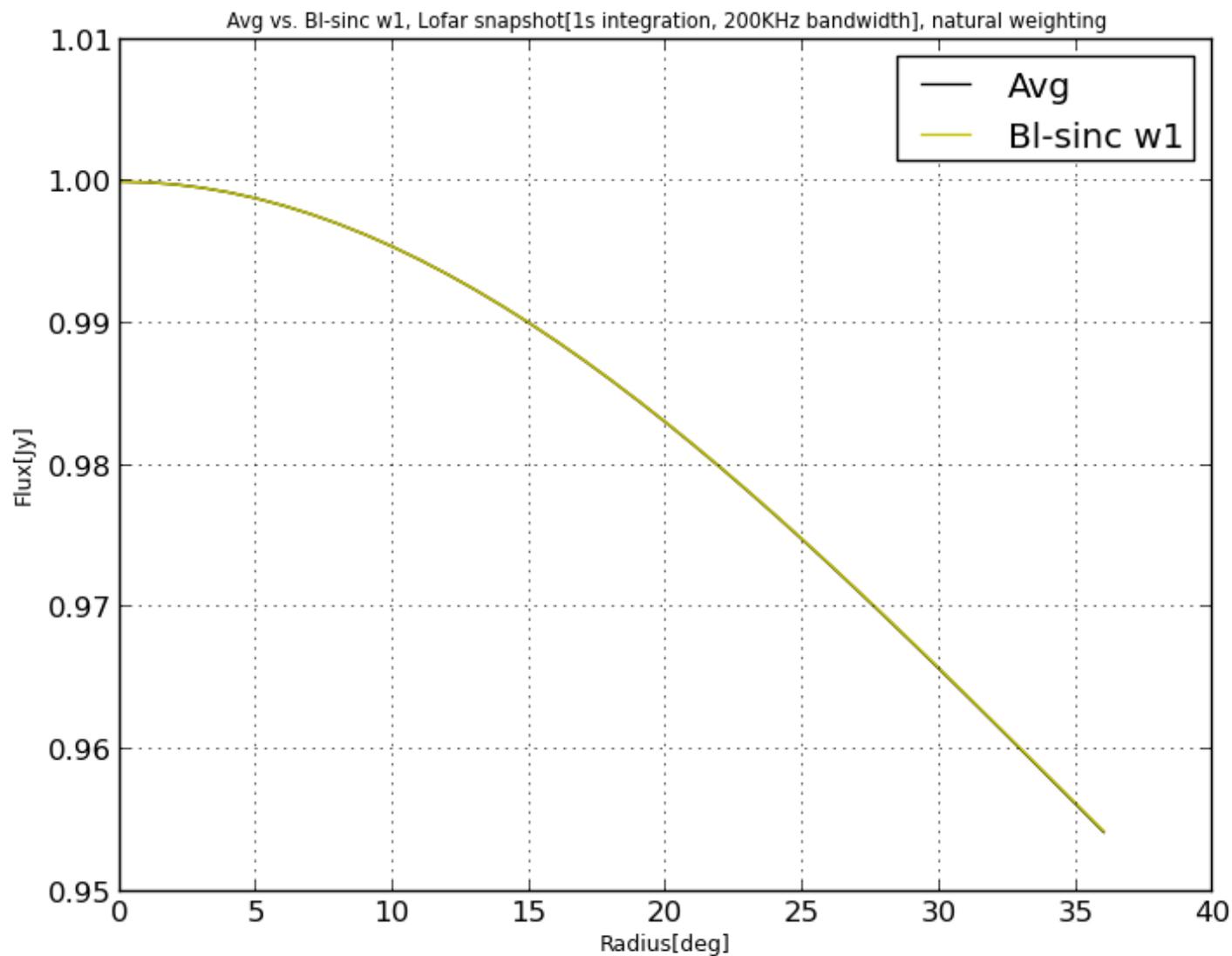
delta-t=1s
delta-f=100kHz



Time/Frequency Smearing (“decorrelation”): For one baseline

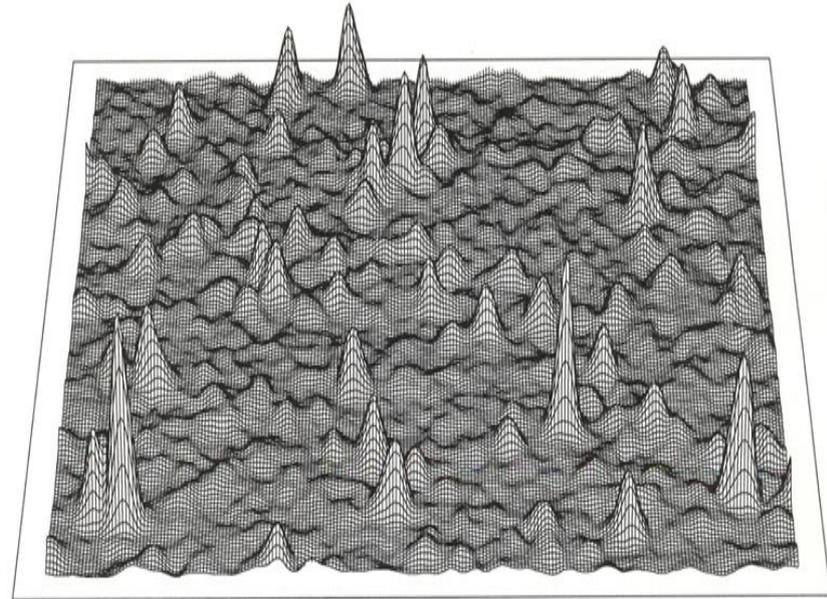
Simulation for NenuFAR
Courtesy: Oleg Smirnov
And Marcellin Atemkeng

delta-t=1s
delta-f=200kHz



Confusion limit

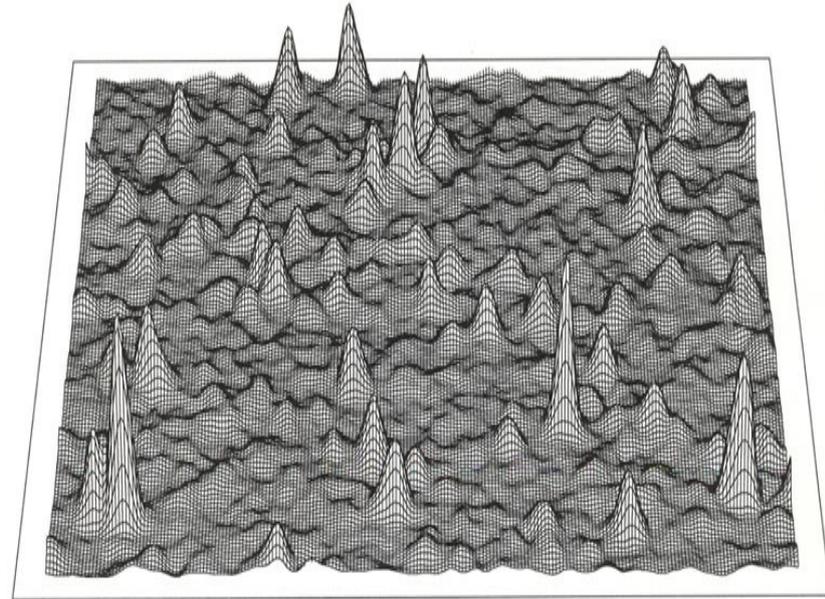
- Source density is too high
Cannot be separated anymore
- Confusion limit:
Depth beyond which **thermal noise** is lower than **confusion noise**



Confusion limit

- Source density is too high
Cannot be separated anymore

- Confusion limit:
Depth beyond which **thermal noise** is lower than **confusion noise**



- **Deflection** (Condon 74) is the intensity observed in a beam taken at random assuming:
 - Poissonian spacial distribution of sources
 - a source count: $n(S) = k \cdot S^{\gamma}$

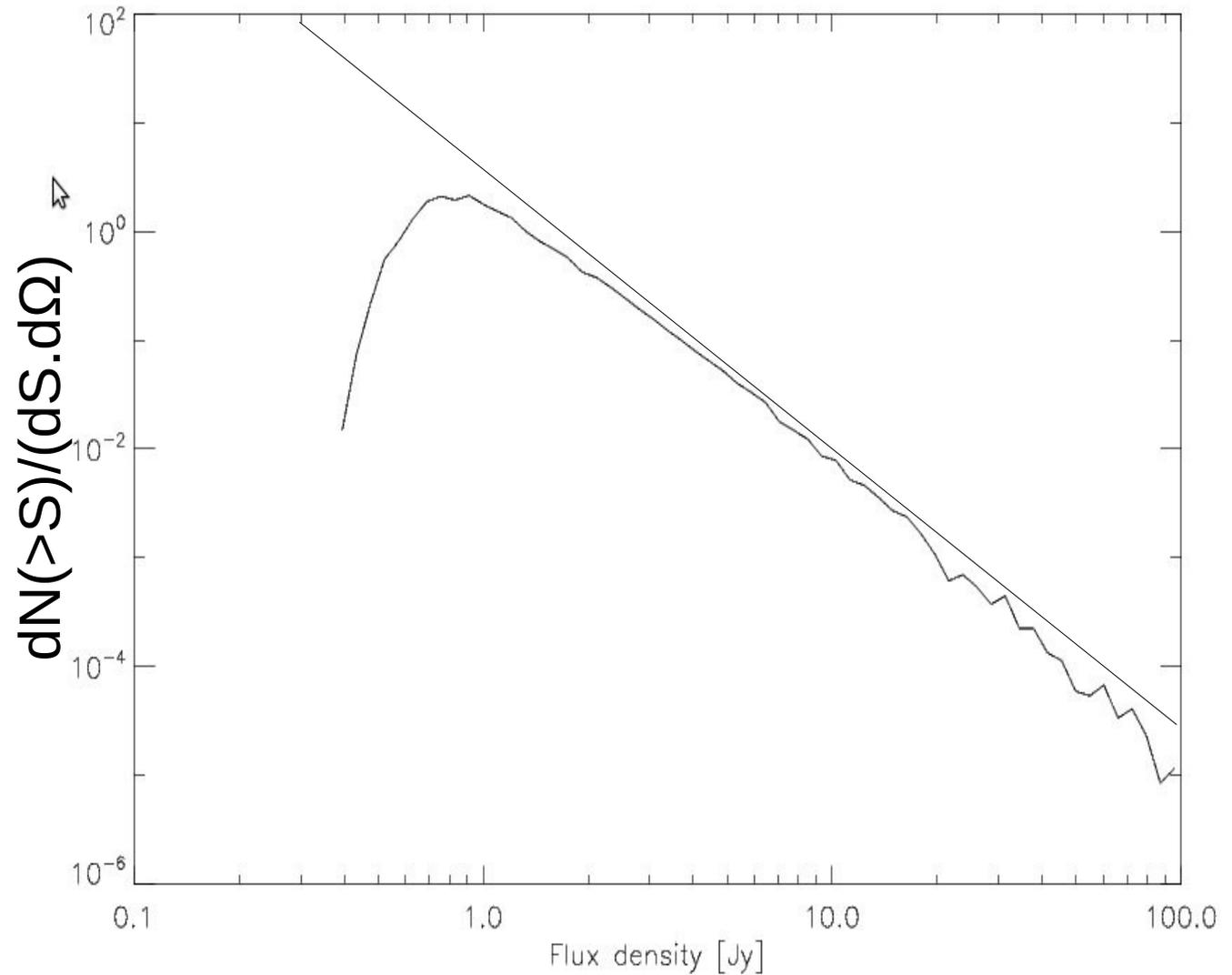
VLSS (74 MHz) source counts

We assume:

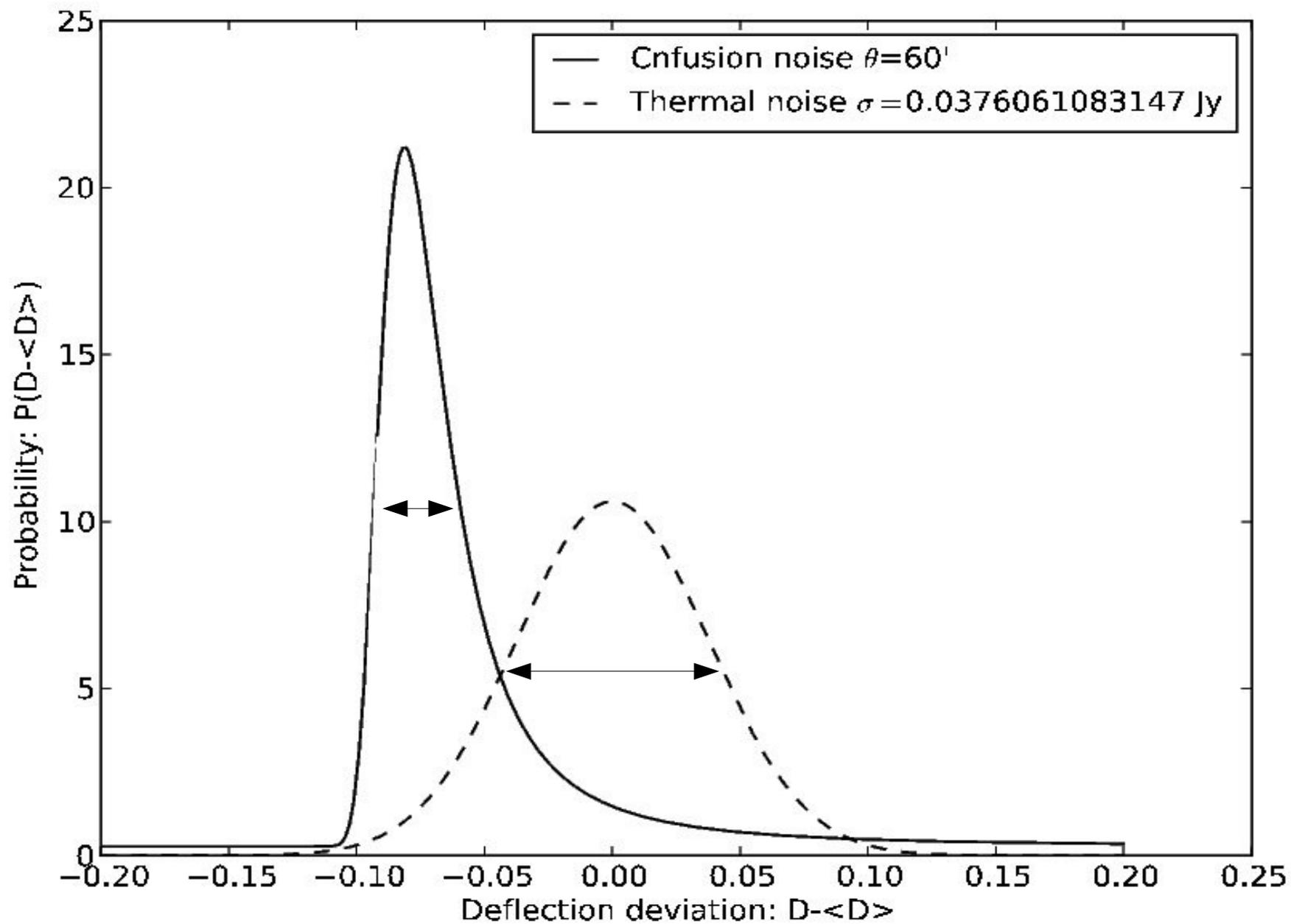
$$n(S) = k \cdot S^{\gamma}$$

Then go to 50

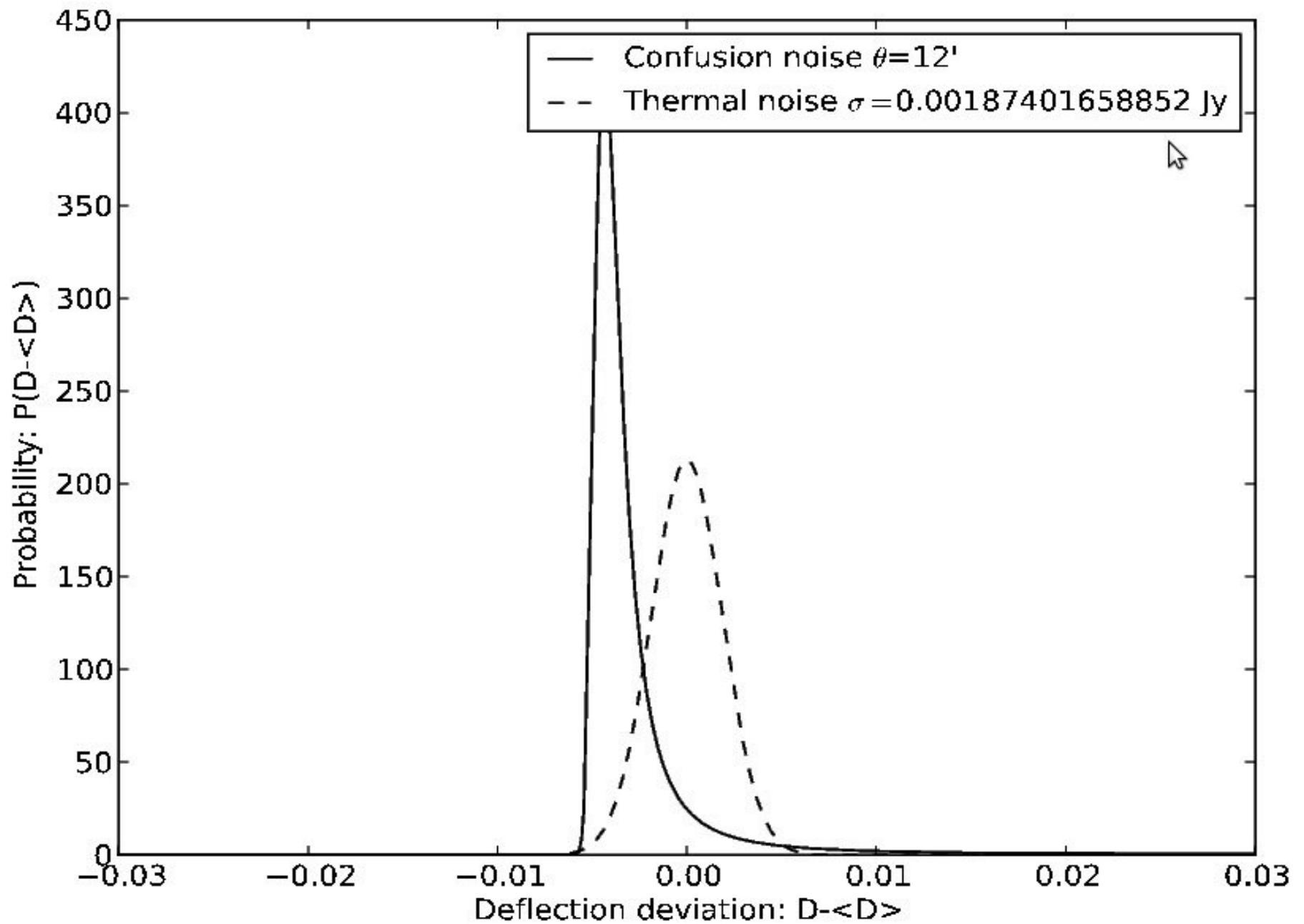
$$\text{MHz: } S = a \cdot \nu^{-0.8}$$



$P(D - \langle D \rangle)$

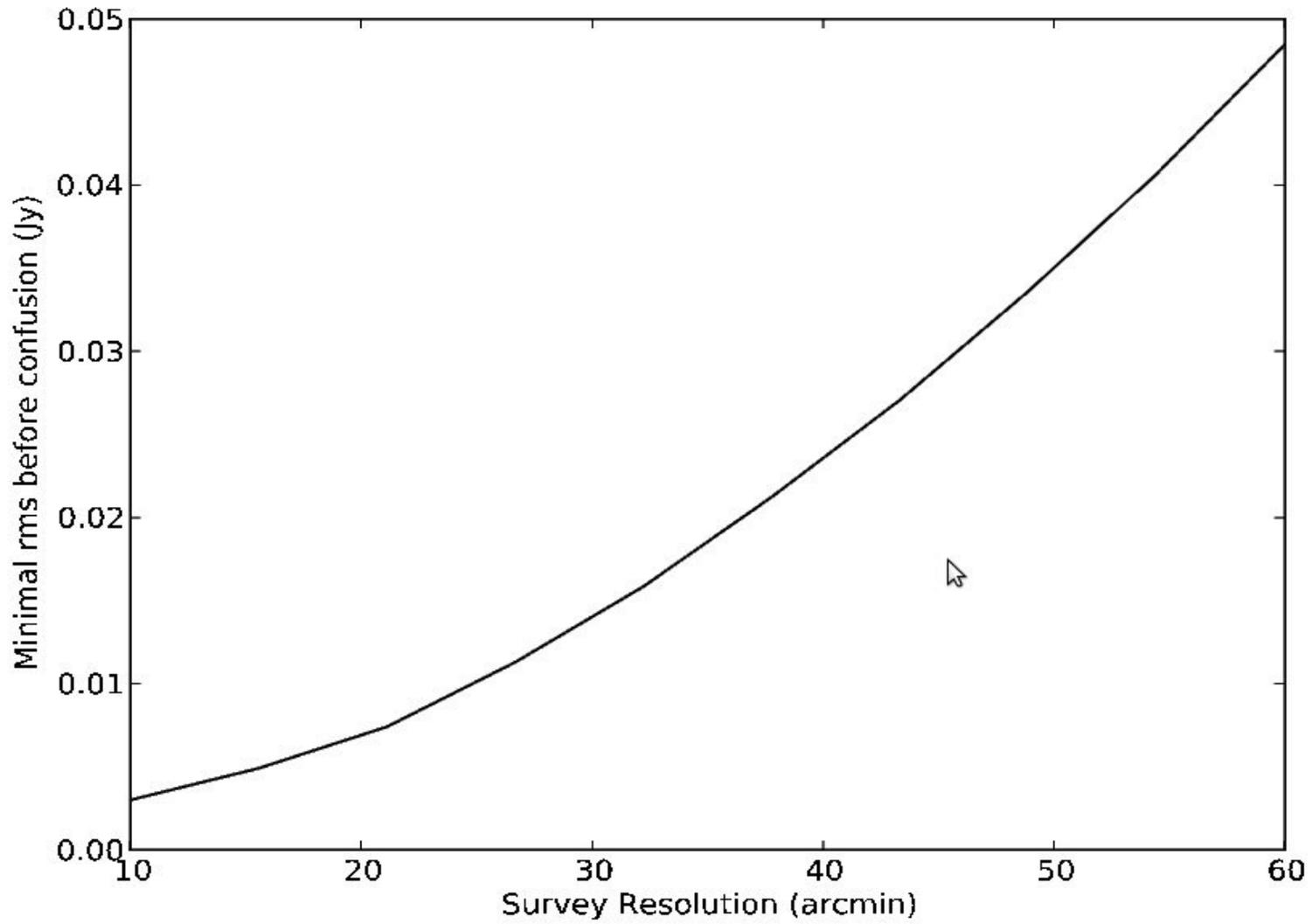


$P(D - \langle D \rangle)$

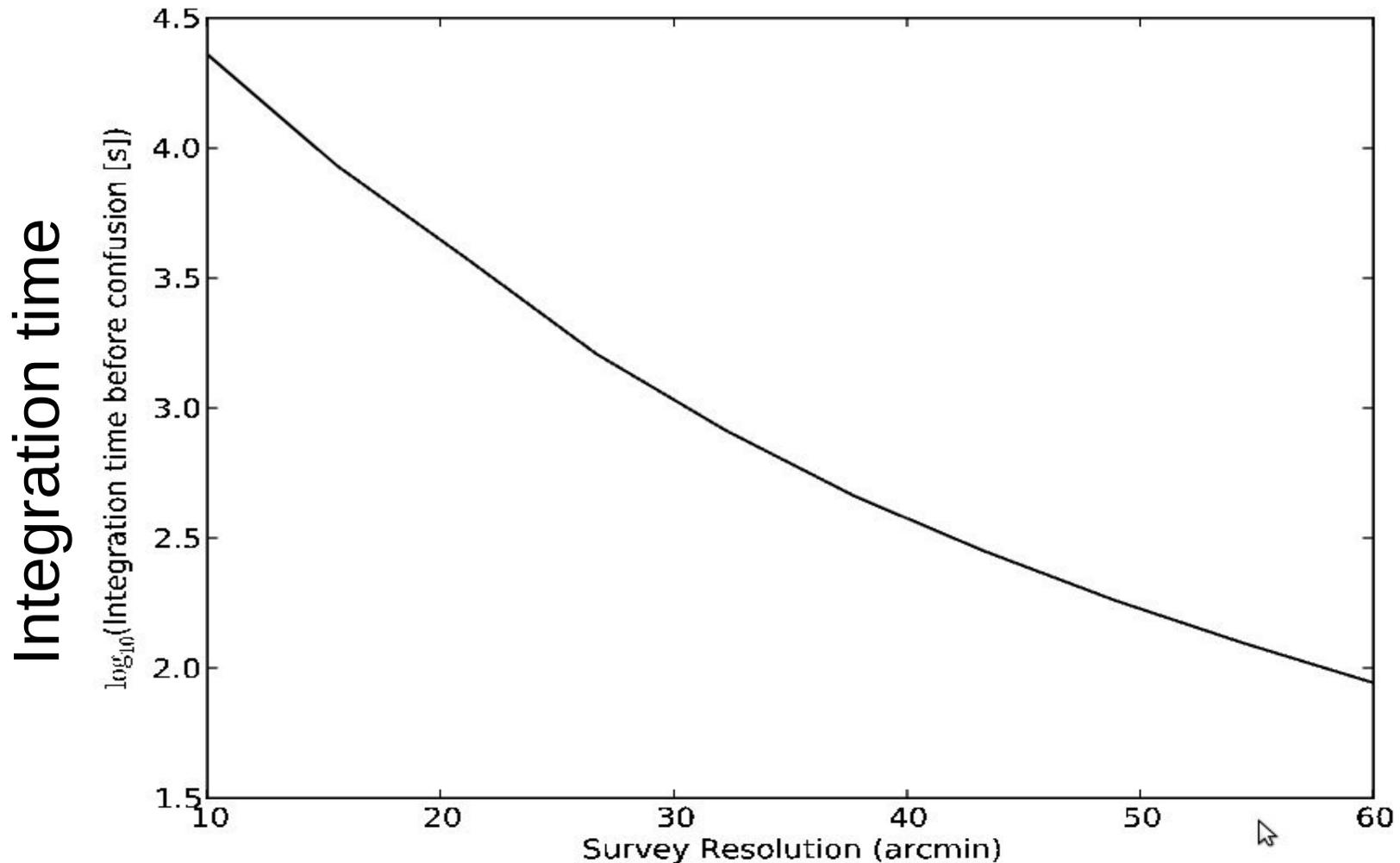


Minimal thermal noise before confusion

Minimum RMS before confusion



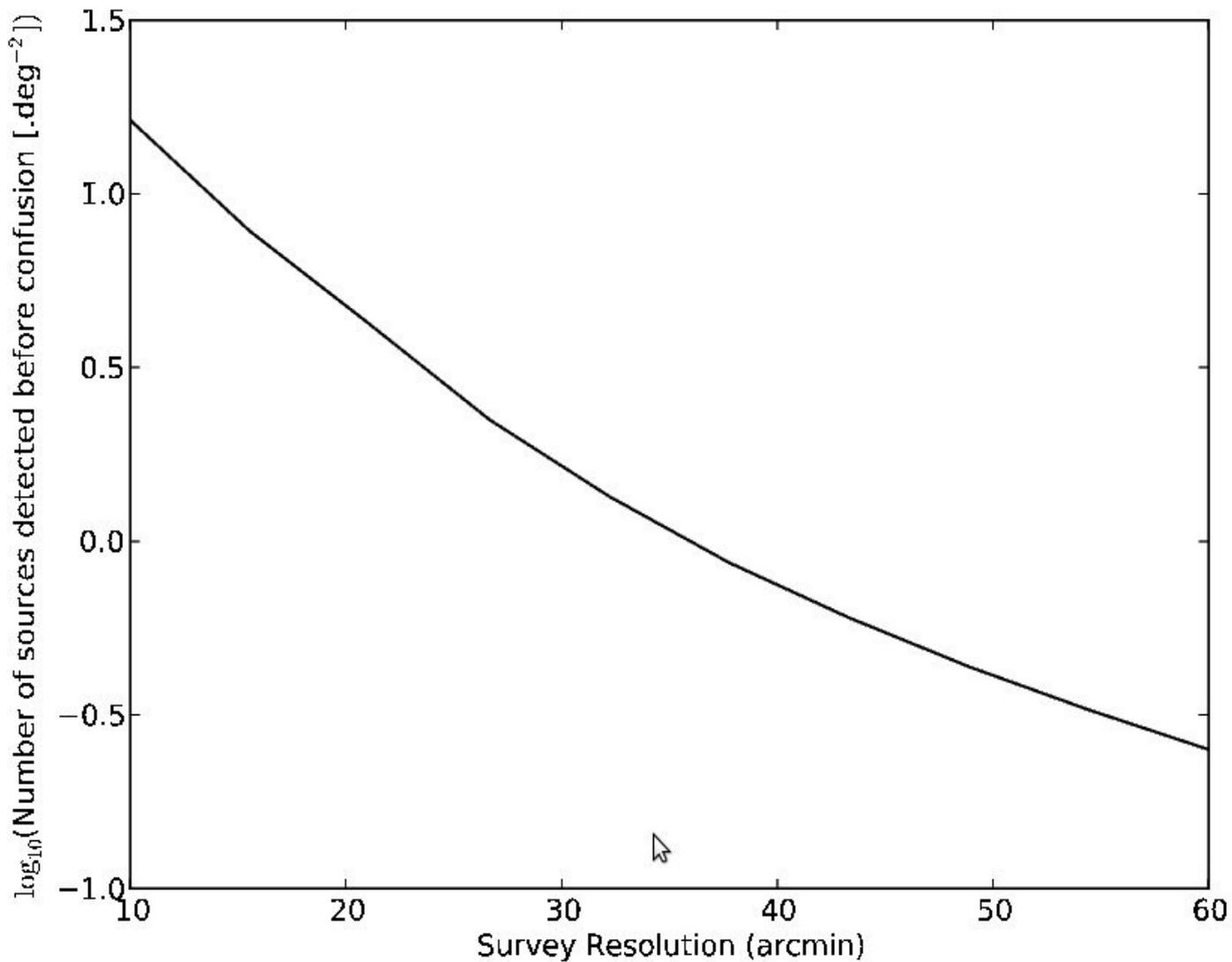
Maximum integration time before confusion



$T_{\text{sky}} = 1.15 \cdot 10^8 / f^{2.5}$ (K): @ $f = 40$ MHz, $T = 20000$ K

Number of sources detected before confusion

Maximum number of resolved sources



Calibration and imaging (Standalone)

- Ionosphere:

- Simple TEC gradient: simplifies a lot the problem
- Faraday rotation, BUT differential Faraday rotation

- Phased array beam:

- Need good model of individual elementary antenna
- Need to measure the errors in cable length (inside mini-arrays)
(we won't be able to correct that because of the analog beam former)

- Calibration (“Classic” calibration):

- Low-frequency skymodels available from MSSS/VLSS
- Importance of short baselines, and extended emission?

- Imaging:

- Ionosphere is present but array is compact
- Fast imaging for transients?

- EoR/Dark Ages:

- The big difference with LOFAR EoR: confusion
- We'll have to think of working on alternative schemes:
 - Individual baseline 1D images
 - Power spectrum as is done for PAPER

Conclusion

NenuFAR: high sensitivity, low resolution

- **Confusion:**

- Confusion limit comes after tens to a hundreds seconds
- Is the main difference with other interferometers

- **Smearing / decorrelation:**

- Is not a problem in terms of amplitude loss

- **Calibration:**

- Good calibration should be trivial
(and inspired by Stefan Wijnholds work on LOFAR stations)
- High quality calibration is more tricky perhaps